# Computer Simulation of Space Interference of Low Frequency Electromagnetic Signals in the Human Body 

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#### Abstract

Low frequency interference devices have a wide range of application in medicine for successful treatment for rheumatism, skin diseases, liver diseases, muscular pain relief, contusions, sprains, chronic diseases. The main target of the article is to present a method of detailed description of low frequency electromagnetic signals in the human body.


Keywords: Space intereferece, Low frequency electromagnetic signals, Human body

## I. INTRODUCTION

In this example a low frequency interference device consists of two electrode couples (electrodes in each couple are parallel each other with rectangular shape). They make electromagnetic signals, whose vectors depend on time. The result of operating at the same time signals is a time dependent signal ( $\vec{E}(t)$ ). Its magnitude and direction change.

The voltage of the first electrode couple has constant low frequency $f_{1}=4000 \mathrm{~Hz}$ and for the second electrode couple it is variable: $\mathrm{f}_{2}=4000 \div 4100 \mathrm{~Hz}$, changing linearly. As a result two different angular frequencies are available $\omega 1, \omega 2$. And the result vector will certainly pass through quasi-resonant frequency of a fixed group of human muscles. The voltage at the end of electrode couples is constant and there are not side effects of inductance. The signal should reach deeply into the space of human body. Formulae below meet this requirements:

$$
\begin{align*}
& \vec{E}_{1}=\left|\vec{E}_{1}\right| \times \cos \left(\omega_{1} \times t\right)  \tag{1}\\
& \vec{E}_{2}=\left|\vec{E}_{2}\right| \times \cos \left(\omega_{2} \times t\right) \tag{2}
\end{align*}
$$

## II. Mathematical Analysis

Tension is a fundamental characteristic to every electromagnetic field. Its absolute value can be estimated, using the principle of Coulomb.

[^0]The tension magnitude in a fixed point can be found by placing there a positive charged particle $Q$ and observing the force between two charged particles.

$$
\begin{equation*}
\vec{E}=\frac{\vec{F}}{Q} \Rightarrow E=\frac{q}{4 \times \pi \times \varepsilon \times r^{2}} \tag{4}
\end{equation*}
$$

The principle of Coulomb is operative only for particle suppliers of energy. If each electrode from the first couple is a particle supplier of energy, the tension in the fixed point will be defined as:

$$
\begin{equation*}
E_{1}=\frac{q}{4 \times \pi \times \varepsilon \times r_{1}^{2}}+\frac{q}{4 \times \pi \times \varepsilon \times\left(d_{1}-r_{1}\right)^{2}} \tag{5}
\end{equation*}
$$

$r_{1}$ and $\left(d_{1}-r_{1}\right)$ are the distances between the fixed point and each "charged particle" of energy.
There are lots of charged particles on the surface of each electrode:

$$
\begin{align*}
E_{1} & =\int_{0}^{\varphi_{1}} \int_{r_{a}}^{r_{b}} \frac{q_{1}}{4 \times \pi \times \varepsilon \times r_{1}^{2}} \times d r d \varphi \\
& +\int_{0}^{\varphi_{2}} \int_{r_{b}}^{r_{b}} \frac{q_{1}}{4 \times \pi \times \varepsilon \times r_{1}^{2}} \times d r d \varphi \\
& +\int_{0}^{\sigma_{1} r_{d}} \int_{r_{c}}^{r_{d}} \frac{q_{1}}{4 \times \pi \times \varepsilon \times\left(\frac{d_{1}}{\cos (\delta)}-r\right)^{2}} \times d\left(\frac{d_{1}}{\cos (\delta)}-r\right) d \sigma \\
& +\int_{0}^{\sigma_{2}} \int_{r_{c}}^{r_{d}} \frac{q_{1}}{4 \times \pi \times \varepsilon \times\left(\frac{d_{1}}{\cos (\delta)}-r\right)^{2}} \times d\left(\frac{d_{1}}{\cos (\delta)}-r\right) d \sigma \tag{6}
\end{align*}
$$

The fixed point is $T$. The perpendicular lines from point $T$ to the first and second electrodes from first couple are denoted respectively by $T T_{1}$ and $T T_{2} . \quad T_{1} T_{2}=d_{1}, \quad T T_{1}=r_{1}$, $T T_{2}=d_{1}-r_{1}$. There is a surface $\boldsymbol{\alpha}$ through line $d_{1} . \boldsymbol{\alpha}$ is perpendicular to both electrodes and its intersection with electrodes is parallel (respectively perpendicular) to electrode's boundaries (fig.3). $\alpha \bigcap Q_{1} Q_{2} Q_{3} Q_{4}=A B$
$\left(A B \| Q_{1} Q_{2}, Q_{3} Q_{4} ; A B \perp Q_{1} Q_{4}, Q_{2} Q_{3}\right)$.
$\alpha \bigcap Q_{5} Q_{6} Q_{7} Q_{8}=C D$
$\left(C D \| Q_{5} Q_{6}, Q_{7} Q_{8} ; C D \perp Q_{5} Q_{8}, Q_{6} Q_{7}\right)$.
$T A=r_{a}, T B=r_{b}, T C=r_{c}, T D=r_{d}$.
Inside Integral Expression: Inside integral covers charged particles, situated in segments $A B$ and $C D$. The result of integrating formula 5 is:

$$
\begin{align*}
E_{1} & =\int_{r_{a}}^{r_{r_{b}}} \frac{q_{1}}{4 \times \pi \times \varepsilon \times r^{2}} \times d r \\
& +\int_{r_{c}}^{r_{d}} \frac{q_{1}}{4 \times \pi \times \varepsilon \times\left(\frac{d_{1}}{\cos (\delta)}-r\right)^{2}} \times d\left(\frac{d_{1}}{\cos (\delta)}-r\right) \\
& =-\left(\frac{q_{1}}{4 \times \pi \times \varepsilon}\right)_{r_{a}}^{r_{b}} \\
& -\left.\left(\frac{q_{1}}{4 \times \pi \times \varepsilon \times\left(\frac{d_{1}}{\cos (\delta)}-r\right)}\right)\right|_{r_{c}} ^{r_{d}} \\
& =\left(\frac{q_{1}}{4 \times \pi \times \varepsilon}\right) \times\left(\frac{1}{r_{a}}-\frac{1}{r_{b}}+\frac{1}{r_{c}}-\frac{1}{r_{d}}\right) \tag{7}
\end{align*}
$$

The plane surface of $\boldsymbol{\alpha}$ leads to the following conclusions:

fig. 1. Plane surface $\alpha$
$r_{1}$ starts at TA and ends at TB, and $\left(d_{1}-r_{1}\right)$ starts at TD and ends at TC. If $r_{1}$ coincides with $r$, then $\left(d_{1}-r_{1}\right)$ coincides with $d$. From triangle $T_{1} T_{2} X$ :

$$
\begin{equation*}
\cos (\delta)=\frac{d_{1}}{d+r} \Rightarrow d=\frac{d_{1}}{\cos (\delta)}-r \tag{8}
\end{equation*}
$$

$d$ is the integration variable for the second integral from formula 7.

Outside Integral Expression:
The second integral takes all the charged particles on the surfaces of the electrodes under consideration. (formula 6.). It is the result of moving of AB and CD over the surface of electrodes at angles $\varphi_{1}, \varphi_{2}, \sigma_{1}, \sigma_{2}$.
$\angle A T Q_{1}=\angle B T Q_{2}=\varphi_{1}, \quad \angle A T Q_{4}=\angle B T Q_{3}=\varphi_{2}$,
$\angle C T Q_{5}=\angle D T Q_{6}=\sigma_{1}, \angle C T Q_{8}=\angle D T Q_{7}=\sigma_{2}$
After integrating formula 7.:

$$
\begin{align*}
E_{1}= & \left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times \int_{0}^{\phi_{1}}\left(\frac{1}{r_{a}}-\frac{1}{r_{b}}\right) \times d \varphi \\
& +\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times \int_{0}^{\phi_{2}}\left(\frac{1}{r_{a}}-\frac{1}{r_{b}}\right) \times d \varphi \\
& +\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times \int_{0}^{\sigma_{1}}\left(\frac{1}{r_{c}}-\frac{1}{r_{d}}\right) \times d \sigma \\
& +\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times \int_{0}^{\sigma_{2}}\left(\frac{1}{r_{c}}-\frac{1}{r_{d}}\right) \times d \sigma \tag{9}
\end{align*}
$$

The rectangular triangles $Q_{1} A T$ and $Q_{4} A T$ have right angle at apex $A$. The rectangular triangles $Q_{2} B T$ and $Q_{3} B T$ have right angles at apex $B$. The rectangular triangles $Q_{5} C T$ and $Q_{8} C T$ have right angles at apex C. The rectangular triangles $Q_{6} D T$ and $Q_{7} D T$ have right angles at apex D . Therefore:

$$
\begin{aligned}
& \cos \left(\delta_{i}\right)=\frac{r_{l}}{r_{l}^{\prime}} \Rightarrow r_{l}=r_{l}^{\prime} \times \cos \left(\delta_{i}\right) \\
& \cos \left(\delta_{i}\right)=\frac{r_{l}}{r_{l}^{\prime \prime}} \Rightarrow r_{l}=r_{l}^{\prime \prime} \times \cos \left(\delta_{i}\right)
\end{aligned}
$$

$$
\begin{equation*}
\text { where : } \delta=\varphi, \sigma ; i=1,2 ; l=a, b, c, d \tag{10}
\end{equation*}
$$

$$
\begin{array}{rlll}
r_{a}^{\prime}=T Q_{1} & r_{b}^{\prime}=T Q_{2} & r_{c}^{\prime}=T Q_{6} & r_{d}^{\prime}=T Q_{5} \\
r_{a}^{\prime \prime}=T Q_{4} & r_{b}^{\prime \prime}=T Q_{3} & r_{c}^{\prime \prime}=T Q_{8} & r_{d}^{\prime \prime}=T Q_{7}
\end{array}
$$

The result from formulas 9. and 10. is formula 11.:
$E_{1}=\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times \int_{0}^{\varphi_{1}}\left(\frac{1}{r_{a}^{\prime} \times \cos (\varphi)}-\frac{1}{r_{b}^{\prime} \times \cos (\varphi)}\right) \times d \varphi$ $+\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times \int_{0}^{\varphi_{2}}\left(\frac{1}{r_{a}^{\prime \prime} \times \cos (\varphi)}-\frac{1}{r_{b}^{\prime \prime} \times \cos (\varphi)}\right) \times d \varphi$ $+\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times \int_{0}^{\sigma}\left(\frac{1}{r_{c}^{\prime} \times \cos (\sigma)}-\frac{1}{r_{d}^{\prime} \times \cos (\sigma)}\right) \times d \sigma$ $+\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times \int_{0}^{\sigma_{2}}\left(\frac{1}{r_{c}^{\prime \prime} \times \cos (\sigma)}-\frac{1}{r_{d}^{\prime \prime} \times \cos (\sigma)}\right) \times d \sigma$

Revised formula is:

$$
\begin{align*}
E_{1} & =\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times\left(\frac{r_{b}^{\prime}-r_{a}^{\prime}}{r_{a}^{\prime} \times r_{b}^{\prime}}\right) \times \int_{0}^{\varphi_{1}} \frac{d \varphi}{\cos (\varphi)}  \tag{11}\\
& +\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times\left(\frac{r_{b}^{\prime \prime}-r_{a}^{\prime \prime}}{r_{a}^{\prime \prime} \times r_{b}^{\prime \prime}}\right) \times \int_{0}^{\varphi_{2}} \frac{d \varphi}{\cos (\varphi)} \\
& +\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times\left(\frac{r_{d}^{\prime}-r_{c}^{\prime}}{r_{d}^{\prime} \times r_{c}^{\prime}}\right) \times \int_{0}^{\sigma_{1}} \frac{d \sigma}{\cos (\sigma)} \\
& +\left(\frac{q}{4 \times \pi \times \varepsilon}\right) \times\left(\frac{r_{d}^{\prime \prime}-r_{c}^{\prime \prime}}{r_{d}^{\prime \prime} \times r_{c}^{\prime \prime}}\right) \times \int_{0}^{\sigma_{2}} \frac{d \sigma}{\cos (\sigma)} \tag{12}
\end{align*}
$$

The solution of the integral is:

$$
\begin{equation*}
\left.\int_{0}^{\varphi_{1}} \frac{d \varphi}{\cos (\varphi)}=-\ln \operatorname{tg}\left(\frac{\left(\frac{\pi}{2}-\varphi_{1}\right)}{2}\right) \right\rvert\, \tag{13}
\end{equation*}
$$

To compute the value of $\mathrm{E}_{1}$ it is necessary to find $r_{i}, r_{i}^{\prime}, r_{i}^{\prime \prime}, \quad i=a, b, c, d ;$ and angles $\varphi_{1}, \varphi_{2}, \sigma_{1}, \sigma_{2}$. The method is:
$>$ Finding the equation of line $T T_{1}$. For that
it is necessary to find the equations of the plains of electrodes by figuring out the determinant below:

$$
\left|\begin{array}{llll}
x & y & z & 1  \tag{14}\\
x_{1} & y_{1} & z_{1} & 1 \\
x_{2} & y_{2} & z_{2} & 1 \\
x_{3} & y_{3} & z_{3} & 1
\end{array}\right|=0
$$

The plane's equation is:

$$
\begin{equation*}
A \times x+B \times y+C \times z+D=0 \tag{15}
\end{equation*}
$$

The normal vector of plains $Q_{1} Q_{2} Q_{3} Q_{4}$ and $Q_{5} Q_{6} Q_{7} Q_{8}$ coincides with the directional vector of $T T_{1}$ : $T_{1} T_{2} \perp Q_{1} Q_{2} Q_{3} Q_{4}$.

Point T is situated on $T T_{1}$. Point T has space coordinates $\mathrm{T}\left(t_{1}, t_{2}, t_{3}\right)$. Therefore the normal vector of plains $Q_{1} Q_{2} Q_{3} Q_{4}$ and $Q_{5} Q_{6} Q_{7} Q_{8}$, called vector ( $\vec{N}$ ), is: $\vec{N}(A, \quad B, \quad C)$.
$T_{1} T_{2}$ equation is:

$$
\begin{equation*}
T_{1} T_{2} \equiv \frac{x-t_{1}}{A}=\frac{y-t_{2}}{B}=\frac{z-t_{3}}{C} \tag{16}
\end{equation*}
$$

> Finding $\mathrm{x}, \mathrm{y}$ and z coordinates of point $T_{1}\left(t_{1}^{\prime}, \quad t_{2}^{\prime}, \quad t_{3}^{\prime}\right)$. For that purpose it is requiring to be solved the system of equations:

$$
\begin{aligned}
& \frac{t_{1}^{\prime}-t_{1}}{A}=\frac{t_{2}^{\prime}-t_{2}}{B}=\frac{t_{3}^{\prime}-t_{3}}{C} \\
& A \times t_{1}^{\prime}+B \times t_{2}^{\prime}+C \times t_{3}^{\prime}+D=0
\end{aligned}
$$

Finding the equation of line $A B$.
$A B \| Q_{1} Q_{2}$. They both have the same directional vector. The equation of $Q_{1} Q_{2}$ is:

$$
\begin{equation*}
Q_{1} Q_{2} \equiv \frac{x-x_{1}}{x_{2}-x_{1}}=\frac{y-y_{1}}{y_{2}-y_{1}}=\frac{z-z_{1}}{z_{2}-z_{1}} \tag{17}
\end{equation*}
$$

And the directional vector has co-ordinates ( $\left(x_{2}-x_{1}\right)$, $\left.\left(y_{2}-y_{1}\right),\left(z_{2}-z_{1}\right)\right)$.Therefore the equation of $Q_{1} Q_{2}$ is:

$$
\begin{equation*}
A B \equiv \frac{a_{1}-t_{1}^{\prime}}{x_{2}-x_{1}}=\frac{a_{2}-t_{2}^{\prime}}{y_{2}-y_{1}}=\frac{a_{3}-t_{3}^{\prime}}{z_{2}-z_{1}} \tag{18}
\end{equation*}
$$

where $A\left(a_{1}, \quad a_{2}, \quad a_{3}\right)$.
$>$ Finding the co-ordinates of point A. $Q_{1} Q_{4}$ 's equation is:

$$
\begin{equation*}
Q_{1} Q_{4} \equiv \frac{x-x_{1}}{x_{4}-x_{1}}=\frac{y-y_{1}}{y_{4}-y_{1}}=\frac{z-z_{1}}{z_{4}-z_{1}} \tag{19}
\end{equation*}
$$

Solving the system of equations:
Solvig syter of

$$
\left\lvert\, \begin{aligned}
& \frac{a_{1}-t_{1}^{\prime}}{x_{2}-x_{1}}=\frac{a_{2}-t_{2}^{\prime}}{y_{2}-y_{1}}=\frac{a_{3}-t_{3}^{\prime}}{z_{2}-z_{1}} \\
& \frac{a_{1}-x_{1}}{x_{4}-x_{1}}=\frac{a_{2}-y_{1}}{y_{4}-y_{1}}=\frac{a_{3}-z_{1}}{z_{4}-z_{1}}
\end{aligned}\right.
$$

The required coordinates are: $A\left(a_{1}, a_{2}, a_{3}\right)$.
Finding the coordinates of points $\mathrm{B}\left(b_{1}, b_{2}, b_{3}\right)$, $C\left(c_{1}, \quad c_{2}, \quad c_{3}\right), D\left(d_{1}, d_{2}, d_{3}\right)$ is in the same manner. The necessary distances are:

$$
\begin{aligned}
& T A=\sqrt{\left(a_{1}-t_{1}\right)^{2}+\left(a_{2}-t_{2}\right)^{2}+\left(a_{3}-t_{3}\right)^{2}} \\
& T B=\sqrt{\left(b_{1}-t_{1}\right)^{2}+\left(b_{2}-t_{2}\right)^{2}+\left(b_{3}-t_{3}\right)^{2}} \\
& T C=\sqrt{\left(c_{1}-t_{1}\right)^{2}+\left(c_{2}-t_{2}\right)^{2}+\left(c_{3}-t_{3}\right)^{2}} \\
& T D=\sqrt{\left(d_{1}-t_{1}\right)^{2}+\left(d_{2}-t_{2}\right)^{2}+\left(d_{3}-t_{3}\right)^{2}} \\
& T Q_{i}=\sqrt{\left(x_{i}-t_{1}\right)^{2}+\left(y_{i}-t_{2}\right)^{2}+\left(z_{i}-t_{3}\right)^{2}}
\end{aligned}
$$

$$
\text { where }: i=1 \div 8
$$

Angles $\varphi_{1}, \varphi_{2}, \sigma_{1}, \sigma_{2}$ comes from formulas 10. The tension $\mathrm{E}_{1}$ in the fixed point T comes from formula 12. Finding tension $E_{2}$ is analogous to finding tension $E_{1}$.

Calculating charged particle on the surfaces of the electrodes: There is a solid body. Its volume is V , surface S , volume charges q . A definition says:

$$
\begin{equation*}
\operatorname{div} \vec{D}=\rho, \tag{20}
\end{equation*}
$$

The result after integrating of it is:

$$
\begin{equation*}
\iiint_{(V)}(\operatorname{div} \vec{D}) \times d V=\iiint_{(V)} \rho \times d V=q \tag{21}
\end{equation*}
$$

In a result of Maksuel's postulate:

$$
\begin{equation*}
\iiint_{(V)} \rho \times d V=\oiint_{(S)} \vec{D} \times d \vec{S}=q \tag{22}
\end{equation*}
$$

and material characteristic:

$$
\begin{equation*}
\vec{D}=\varepsilon \times \vec{E} \tag{23}
\end{equation*}
$$

is Gauss's law:

$$
\begin{equation*}
\oiint_{(S)} \vec{E} \times d \vec{S}=\frac{q}{\varepsilon} \tag{24}
\end{equation*}
$$

Putting it into practice for electrodes of the low frequency interference device, it assumes the following structure:

$$
\begin{align*}
& \oiint_{(S e)} \vec{E} \times d \vec{S}=\iint_{(S e)} E \times d S \\
& \quad=E \times \iint d S=E \times S e=\frac{q}{\varepsilon} \tag{25}
\end{align*}
$$

The charge on the surface of the electrodes is:

$$
\begin{equation*}
q=E \times \varepsilon \times S e=\frac{U}{d} \times \varepsilon \times S e \tag{26}
\end{equation*}
$$


fig. 2. Charged particles on electrodes
There is tension only at the down side of the electrode.
$E=\frac{U}{d}$, U-voltage at the end of each electrode couple, d distance between electrodes. The charges on the surfaces of the couples are $q_{1}$ and $q_{2}$.

Finding The Vectors of The Tension: Using formulas 1. and 2. Total vector is: $\vec{E}=\vec{E}_{1}+\vec{E}_{2}$

It is a sum of space coordinates of $\vec{E}_{1}$ and $\vec{E}_{2}$.

$$
\begin{equation*}
E_{i}=E_{1 i}+E_{2 i} \quad i=x, y, z \tag{27}
\end{equation*}
$$

## III. CONCLUSION

1. A mathematical analysis of space-temporal configuration of low-frequency currents in the case of interference in the human body is given in the paper.
2. The presented mathematical description can be a base for computer simulation of space-temporal configuration of lowfrequency currents in the case of interference in the human body is given in the paper.
3. An optimization of apparatus for intereferent currents in the process of design can be obtained using the above mentioned computer simulation

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