## Interactive Environment for Solving Multiple Objective Programming Problems GENS-IM

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*Abstract* – The Generalized Scalarazing Interactive Method GENS-IM unifies a number of fifteen available particular interactive methods designed to solve multiple objective programming problems. The scalarizing problem of each method can be derived by setting appropriate values to the parameters of the GENS-IM. The method is implemented in an user-friendly environment. The Decision Maker (DM) can enter/edit his/her multiobjective problems and he/she can use in interactive mode several scalarizing methods in one solution process. The choice of a method is organized in an implicit way on the base of DM's preferences.

Keywords - Multiple Objectives, Optimization, Software

#### I. INTRODUCTION

In many practical problems the decision making is based on more than one objective. Unfortunately these objectives are conflicting in nature, i.e. there does not exist a solution optimizing all the objectives simultaneously. The Decision Maker (DM) must make a decision by compromise among a set of equally good solutions.

We consider the following formulation of multiple objective optimization problem:

$$min \ \{f_l(x), \, ..., \, f_k(x)\}$$
(1)

subject to: 
$$g_i(x) \le 0; \quad i = 1,...,m;$$
 (2)

$$x \in \mathbb{R}^n, \tag{3}$$

where *x* is an *n*-dimensional vector of variables  $x_j$ , j = 1,...,n which accept continuous and/or discrete values. The objective functions  $f_i(x)$ , i = 1,...,k are convex. The constraint functions  $g_i(x)$ , i = 1,...,m are also convex.

The solutions of problem (1) - (3) are the so called Pareto optimal solutions [1, 2]:

Definition A solution  $\mathbf{x}^{(1)}$  is said to be Pareto optimal if and only if there does not exist another solution  $\mathbf{x}^{(2)}$  such that  $f_j(\mathbf{x}^{(2)}) \leq f_j(\mathbf{x}^{(1)})$  for j = 1,...,k and strict inequality holds for at least one index.

The aim of methods for solving Multiple Objective Programming Problems (MOPPs) is to assist the DM to choose one compromise Pareto optimal solution which satisfies to the greatest extent his preferences related to the values of each of the criteria. Different approaches and methods are suggested in literature [1-4]. They differ in the way the DM sets his/her preferences and in the way they scan the set of Pareto solutions. One of the most developed and

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<sup>2</sup>P. Zhivkov is with the ZH Software Ltd., 1000 Sofia, Bulgaria, Email: pzhivkov@dir.bg widespread methods for solving MOPPs are the interactive methods [28]. This is due to their basic advantages – a small part of the Pareto optimal solutions is generated and evaluated by the DM; in the process of solving the multicriteria problem, the DM is able to learn regarding the problem; the DM can change his/her preferences in the process of problem solution.

The choice of MCDM method is not trivial and depends on a number of factors such that the type of solved problem, the DM preferences, on the logic of the solution process. Sometimes it is desirable to change the strategies for solving. In other words to solve the problem with other method(s). Therefore it is convenient to create platforms allowing that. One approach is to create generalized methods unifying several different methods - [24,25, 18]. Development of software environments based on such generalized formulations can be very useful for real decision processes.

An interactive environment developed on the base of generalized interactive method GENS-IM is presented in the paper.

#### II. THE GENERALIZED METHOD GENS-IM

The scalarising problem GENS [26] unifies the following scalarising problems: scalarising problem of weighted sum [1], Tchebycheff scalarising problem [13], scalarising problem of  $\varepsilon$  - constraints [19], scalarising problem of STEM (STEP method) [12], scalarising problem of STOM (Satisfying Trade-Off Method) [14], scalarising problem of GUESS method [15], achievement scalarising problem (Reference Point method) [4, 16], scalarising problem MRP (Modified Reference Point) [29], VIG scalarising problem [6,7], scalarising problem of reference directions RD [8, 27], RD2 scalarising problem [9], NIMBUS scalarising problem [20], DALDI scalarising problem [21,22].

We add also NRNP - new reference-neighborhood scalarising problem [23].

The generalized scalarizing problem GENS is defined as: Minimize T(x)

$$T(x) = \max\left(\max_{k \in K^{\geq}} (F_{k}^{1} - f_{k}(x))G_{k}^{1}R_{1}\max_{k \in K^{\leq}} (F_{k}^{2} - f_{k}(x))G_{k}^{2}R_{2}\right)$$

$$\max_{k \in K^{\leq}} (F_{k}^{3} - f_{k}(x))G_{k}^{3}R_{3}\max_{k \in K^{\geq}} (F_{k}^{4} - f_{k}(x))G_{k}^{4} + \sum_{k \in K^{0}} (F_{k}^{5} - f_{k}(x))G_{k}^{5} + \rho\left(\sum_{k \in K^{\geq}} (F_{k}^{1} - f_{k}(x))G_{k}^{1} + \sum_{k \in K^{\leq}} (F_{k}^{2} - f_{k}(x))G_{k}^{2} + \sum_{k \in K^{\leq}} (F_{k}^{3} - f_{k}(x))G_{k}^{3} + \sum_{k \in K^{\geq}} (F_{k}^{4} - f_{k}(x))G_{k}^{4} - \sum_{k \in K^{=} \cup K^{>}} f_{k}(x)G_{k}^{5}\right)$$

$$(4)$$

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subject to:

$$f_k(x) \ge f_k, \quad k \in K^{\sim} \cup K^{-} \tag{5}$$

$$f_k(x) \ge f_k - D_k, \quad k \in K^{\leq}$$
(6)

$$f_k(x) \ge f_k - t_k^{-}, \quad k \in K^{><} \tag{7}$$

$$f_{k}(x) \le f_{k} + t_{k}^{\dagger}, \quad k \in K^{\times}$$

$$\tag{8}$$

$$x \in X$$
 (9) where

- ρ is a small positive number;
- K is the set of objectives' indices;
- $G_k^1, G_k^2, G_k^3, G_k^4, G_k^5$  are scalarizing coefficients;  $F_k^1, F_k^2, F_k^3, F_k^4, F_k^5$  are parameters, conce concerning aspiration, current or other levels of objectives' values;
- $R_1, R_2, R_3 \in \{"+", ", "\}$
- $D_{\kappa}$  is the amount by which the DM agrees to deteriorate the objective value  $f_k$  (0<  $D_{\kappa} < \infty$ );
- $f_k$  the current objective value of  $f_k(x)$ ,  $k \in K$ ;
- $K^{\geq}$  is the set of objectives indices for which the DM wants to improve the corresponding objective values till to the given aspiration levels  $F_{k}^{1}$ ;
- $K^{>}$  is the set of objective indices for which the DM wants to improve the corresponding objective values;
- $K^{\leq}$  is the set of objective indices for which the DM agrees to deteriorate the corresponding objective values till to the given aspiration levels  $F_k^2$ , i.e.  $F_k^2 \ge f_{\kappa} - D_k$ ;
- $K^{<}$  is the set of objective indices for which the DM agrees to deteriorate the corresponding objective values;
- $K^{=}$  is the set of objective indices for which the DM wants their current values not to be deteriorated;
- $K^{><}$  is the set of objective indices for which the DM wants to change the corresponding objective values in some intervals;
- $t_k^-$  and  $t_k^+$  are the lower and upper bounds for the objective values of the objective  $f_k(x)$  with index  $k \in K^{><}$ :
- $K^0$  is the set of objective indices for which the DM does not set explicitly aspirations to change the corresponding objective values.

Here we assume that  $K^{\geq} \neq \emptyset$  and/or  $K^{\geq} \neq \emptyset$  and  $K^0 \neq K$  without loss of generality.

By setting appropriate values to the parameters of GENS we generate the scalarizing problem of the one of the above mentioned methods.

#### **III. THE INTERACTIVE ENVIRONMENT**

The interactive environment GENS-IM consists of the following main parts: interface module, parser module and solver module.

The interface module realizes the communication with the DM in the solution process.

The parser module is used to analyze the input data according to the developed extension of LP format in multiple objectives' case. LP file format is the native LPsolve format for providing LP models via an ASCII file to the solver.

The problem is solved with solver module. The generalized scalarizing method GENS-IM is realized in the solver.

Via interface module the DM enters the problem solved or edits it later - see Fig. 1. Input data format is very similar to the mathematical notation.

Also the DM sets information about the type of desired solution - integer or continuous, weak or strong Pareto optimal.

The interface module organizes also the communication with the DM to set his/her preferences in the most convenient and understandable form for him/her. He/she can choose among a set of four possible types of preferences: criteria weights, optimize one object vs. rest of others, reference points in the objective space, number of solution along a specified direction and classification of the objectives.

The initial solution could be generated authomatically or the DM sets the desirable objective values. The DM could set also the assessment of the relative importance of objectives or for the desired changes of their values.

After analysis of entered information a set of scalarizing problems is suggested for generating the next (weak) Pareto optimal solution (single or a defined number in advance). If the DM is not an expert in the area of multiobjective optimization, he/she can find the solution(s) by the help of the automatically suggested scalarizing problem. Usually this is the most popular scalarizing rpoblem from the corresponding group. For example, if the DM has chosen to work with aspiration levels (reference point) he/she is suggested a set of the following scalarizing problems: Chebyshev's, STEM, STOM, GESS, Wierzbicki's, MRP. In this case the DM is offered by default a scalarizing problem of Wierzbicki's method.

The DM can save the chosen solution and to use it later as an initial solution for new problem solving with another type of preferences or new of the same type. When solving integer problems with high dimensionality the DM can start seraching with continuous variables while exploring the possibilities of the problem until obtaining satisfactory objective values. After that, the closest feasible integer solution can be found or to start a new search with integer variables.

File Help		
; this is a test problem		
max f1 = x1 :		
max f2 = x2;		
s.t.		
c1: 3x1+10000x2 <= 3000;		
c2: x1<=800;		
; bounds		
x1>=0; x2>=0;		
x1 integer		
•		τ.
Select a preference type:	Help: Requirements:	
Criteria weights	<ul> <li>STOM - scalarising problem of STOM (Satisfying Trade-Off Method)</li> </ul>	
-One objective vs. the rest of others	Input parameters: The DM sets the reference point in the objective space. Its	
Reference point in the objective space	coordinates are the desired or acceptable objective values for the DM. The	
<ul> <li>Improving only a part of the objectives</li> </ul>	Parterence point must not dominate the ideal point.	
Use marginal rates of substitution	Output parameters: one (weak) Fareto optimal solution.	
Maximally remote from the nadir vector	Step: 2/2	
Set reference points for all objectives	More details     Get Nearest Integer     Solve     < >	
Min/ Ideal Nadir Step1 Preference Step2	Preference	
Mac 1 000 0 0.0000 500 00 0.0000		
t1 = Max. 800.0000 0.0000 400.0300 Improve to 70. 666.6.		
f2 = Max 0.3000 0.0000 0.1800 Worse to 0.10 0.1000		
An optimal solution was obtained.		1

Fig. 1. The interface of the interactive environment

The input data and generated solutions are stored at each iteration in a XML file.

This interactive environment is written on Dot.Net. It works under Windows environment. At present it is designed to solve linear integer or continuous MOPPs.

### IV. CONCLUSION

The software environment GENS-IM is designed for users with different levels of knowledge in the area of multiple objective optimization. It has user friendly interface. The system can be used for research studies, educational training, practical implementations.

The DM can model, solve and study the properties of the problem. He/she has the possibility to use the history of the problem' solutions and this way being more confident in the final choice. The built in method GENS-IM enables switching between different methods, using different types of preferences.

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